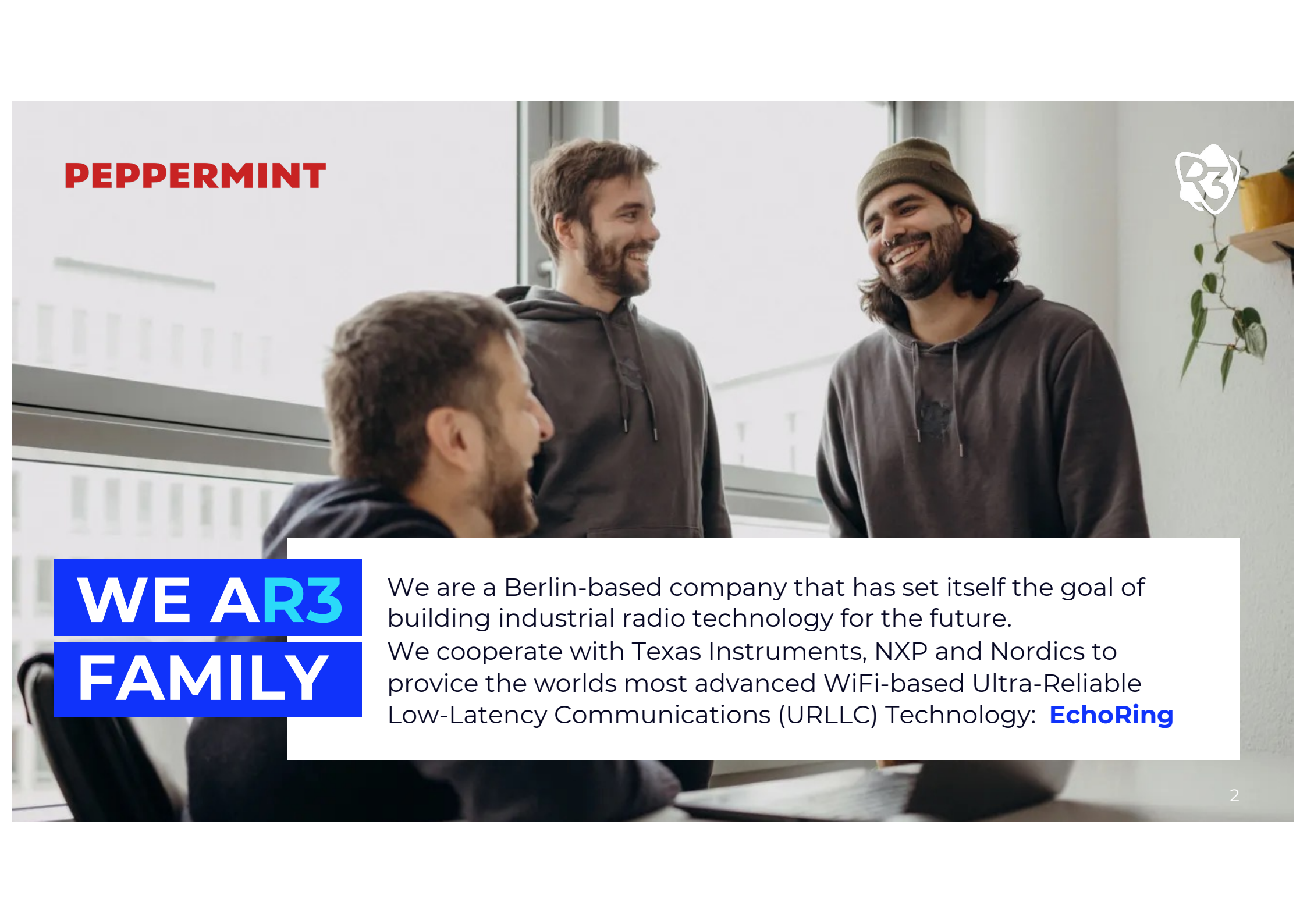


WIRELESS **PROFINET** AND BEYOND **DECT NR+** FOR INTRA-LOGISTICS

DECT World, November 12th, 2025
Dr. Mathias Bohge, R3 Solutions GmbH



PEPPERMINT

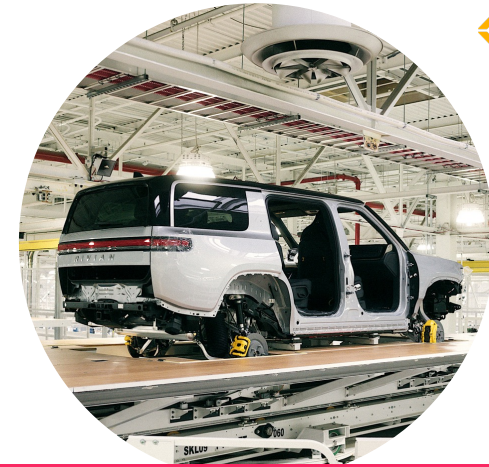
**WE AR3
FAMILY**

We are a Berlin-based company that has set itself the goal of building industrial radio technology for the future.

We cooperate with Texas Instruments, NXP and Nordics to provide the world's most advanced WiFi-based Ultra-Reliable Low-Latency Communications (URLLC) Technology: **EchoRing**

BRIDGE E

- Dedicated OT¹ network that operates parallel to Wi-Fi
- 1000x more reliable than Wi-Fi
- Guaranteed channel access
- Designed safety & control data traffic



RIVIAN

COMPATIBLE WITH



EtherNet/IP



EtherCAT

Safety over
EtherCAT

EDGE X

- Wi-Fi 6E client & Micro Access Point
- Powerful iMX-8 processor with ML accelerators
- Soft PLC for various industrial protocols
- Various I/Os and additional two CAN interfaces
- Highest security and TSN-ready



Rockwell Automation

Automation Fair®

1 – OT: operational technology, 2 – PLC: programmable logic controller

EXAMPLE SKILLET LINE



RIVIAN



System Length: 660 m incl. repatriation

Network Devices: # 124 (among #80 skillets)

Wireless Subnets: # 12 with seamless roaming

Communication: Control + Safety + Monitoring

Service: Full-Service Package



EXAMPLE WAREHOUSE SOLUTION



Solution Size: 30 m x 10 m

Network Devices: # 18 thereof # 16 shuttles

Wireless Subnets: # 1 per Machine

Communication: Control

Service: Solution Development Support



EXAMPLE OVERHEAD CRANE

Communication Area: 300 m x 25 m

Network Devices: # 6 with # 3 Cranes

Wireless Subnets: # 3 with Seamless Roaming

Communication: Control

Service: On-site Commissioning Support



EXAMPLE AMR SOLUTION



Communication Area: 30 m x 30 m

Network Devices: # 20 thereof # 16 AMRs

Wireless Subnets: # 4 dedicatec Safety Zones

Communication: Safety

Service: Solution Development Support

servis
control



SAFETY

GÖTTING

CAMERA AMR

A camera-mounted robot moves around the artist, capturing a dynamic 360-degree immersive video

Stationary LiDAR unit

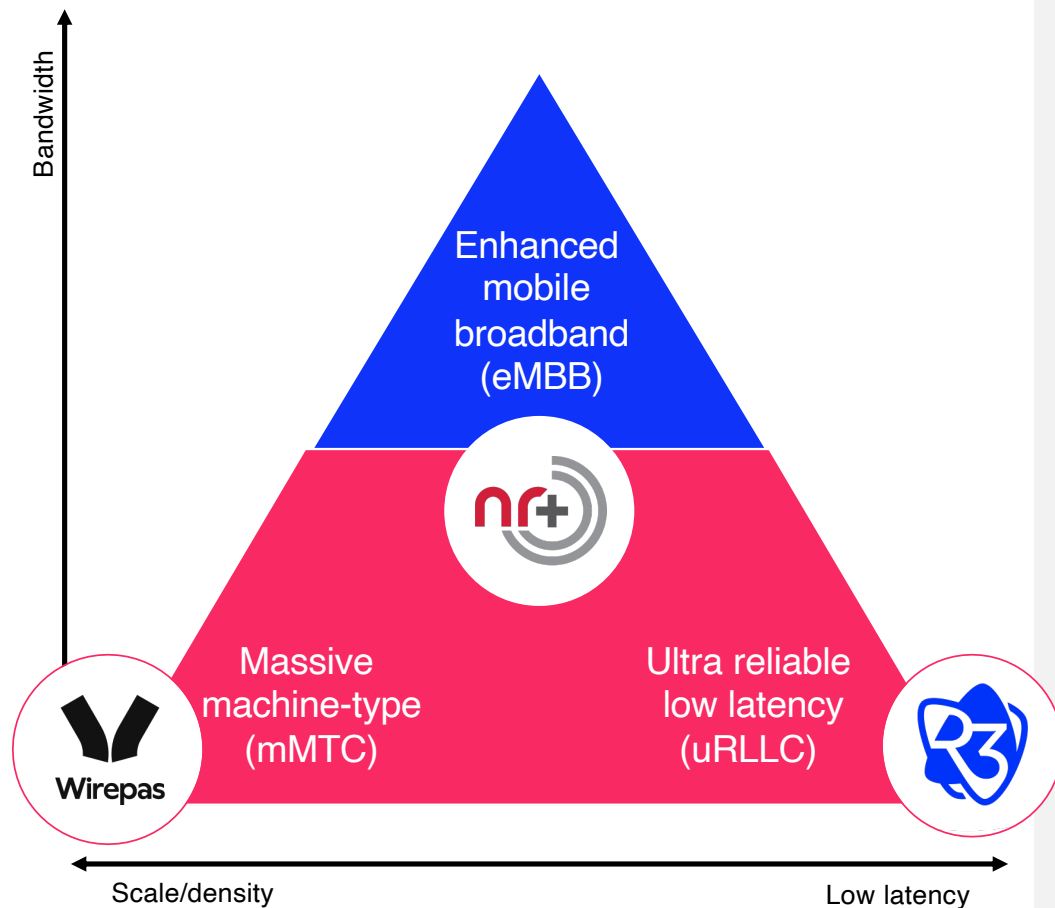
- SLAM-based localization
- Person tracking
- Virtual stage for the person
- Obstacle detection
- Robot trajectory planning

10ms communication cycle for control data exchange between LiDAR unit and robot

Not receiving control data for **50ms** triggers emergency stop on the robot



MERCI PROJECT



The MERCI project is developing solutions for private 5G networks based on **ETSI DECT-2020 NR**, a new standard that has been approved by the ITU-R as IMT-2020 technology.

In collaboration with German and French companies, hardware and software solutions are being built based on system-in-package solutions from the NRF91 series from the manufacturer **Nordic Semiconductor**.

R3 is building a **URLLC stack** for the AGV manufacturer **Götting** based on EchoRing technology to control its AGVs.





Solutions
Edge

EDGE D

STARTING 2026

Based on latest YANG-model architecture (borrowed from its Wi-Fi brother EDGE X), EDGE D will become the first **fully managed DECT NR+ client** on the planet.

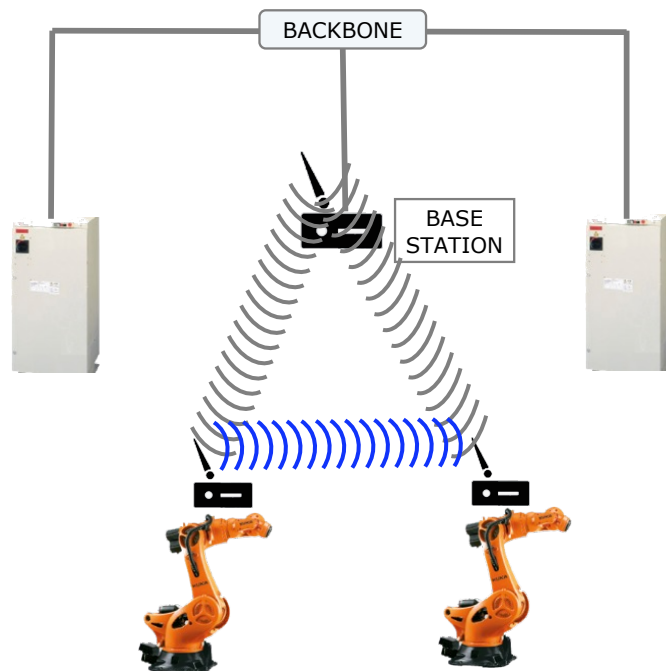
Its compact form factor is ideal for small AGV/AMR units and optimizes space utilization. Advanced power management features improve duty cycles and reduce power consumption, making **EDGE D** the ideal solution for OEMs looking to integrate **DECT NR+** into their **AGV/AMR systems**.

Wireless safety support / URLLC will be available via software add-ons.

EDGE D **URLLC** ADD-ON

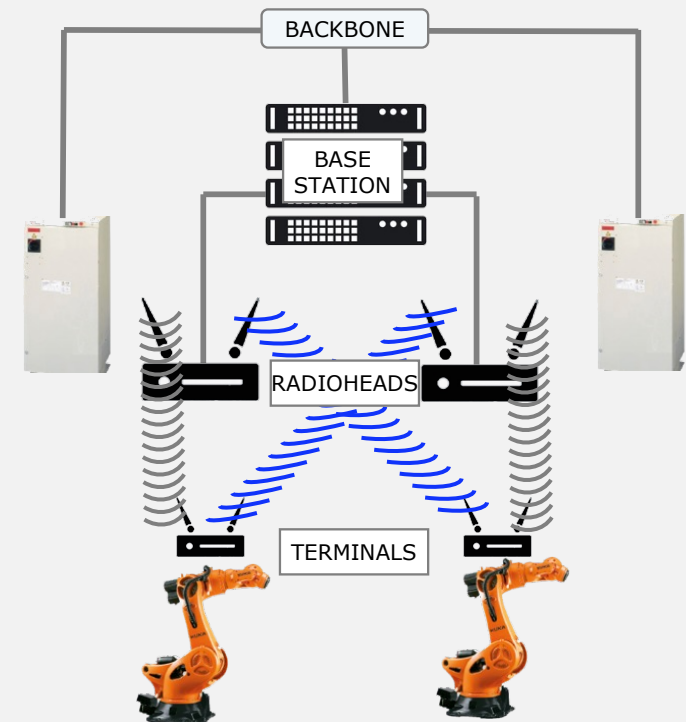


DECT NR+: DISTRIBUTED MESH URLLC (based on massive cooperation)



FREQUENCIES	
5G + DECT	5G
NETWORK SETUP	
use-case centric	infrastructure
MIMO	
NO	YES
RADIATED POWER	
low	high
OVERALL COST	
low	high

3GPP NR: CENTRALIZED URLLC (based on coordinated multipoint)





Solutions
Edge

SUMMARY

EDGE D IS STARTING IN 2026

- fully managed DECT NR+ device
- designed for **intra-logistics**
- YANG-model architecture
- gNMI / netconf interfaces
- wireless safety / URLLC add-ons



approach us for further information



THANK YOU!

Dr. Mathias Bohge

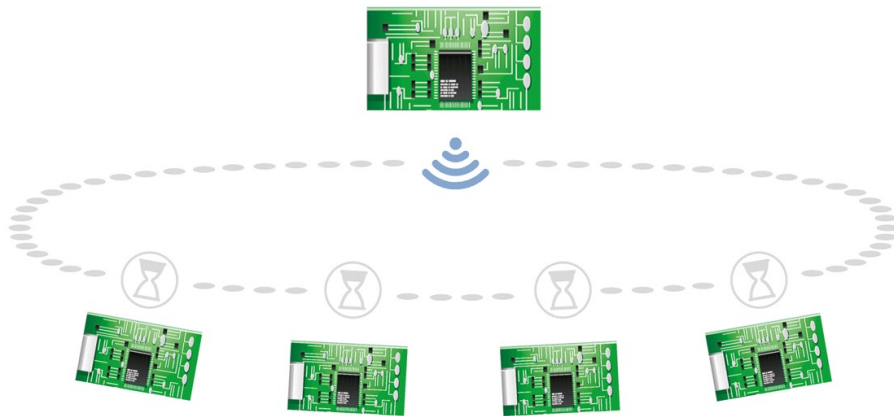
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DETERMINISMUS DER **RING** IM ECHORING



KOOPERATION DAS **ECHO** IM ECHORING

